# SMARC\_RK3568\_Debian User Manual



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#### **REVISION HISTORY**

Time	Version	Purpose	Author	Comment
2023/2/8	1.0	Initial	wj	



# 1. Linux OS Installation

Burning tool preparation: USB Type-A cable\*1、12V power supply\*1



# **1.1 Driver Installation**

Download and install DriverAssitant\_v5.0 on PC.

Link: https://pan.baidu.com/s/1rC9wLfxLoHSrSYnoMdPbjA

Key: znmg

 ${\sf Double-click} \ to \ open \ {\sf DriverAssitant\_v5.0}, \ then \ {\sf double-click} \ {\sf DriverInstall.exe} \ and$ 

click "Driver Install", click OK after success.

确定

▲ 瑞芯微驱动助手 v5.0	×
驱动安装	驱动卸载
DriverInstall X	
安装驱动成功.	

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# 1.2 Upgrade Firmware

Download and unzip the firmware, double click to open RKDevTool\_Release>RKDevTool.exe.

#	口存储	地址	名字	路径	1		
1	<b>V</b>	0x00000000	loader	\rockdev \MiniLoaderAll. bin			
2		0x000000x0	parameter	\rockdev\parameter. txt	6. J		
3	<b>v</b>	0x00004000	uboot	\rockdev\uboot.img			
4	<b>V</b>	0x00006000	nisc	\rockdev\misc. ing			
5	<b>v</b>	0x000080000	boot	\rockdev\boot.ing			
6	<b>v</b>	0x00028000	recovery	\rockdev\recovery.ing			
7		0x00068000	backup				
8	<b>V</b>	0x01C78000	oen	\rockdev\oen. ing			
9	<b>v</b>	0x00078000	rootfs	\rockdev\rootfs.ing			
10	<b>V</b>	0x01D18000	userdata	\rockdev\userdata.ing	1.00		
Load	er:	执行	切换	设备分区表 清空			

Click upgrade firmware, then click firmware, select rockdev->update.img to upload.

▲ 瑞芯微开发工具 v2.92	× 打开	>
下载镜像 升级固件 高级功能	查找范围(I): 📴 rockdev 🗸 🎯 🎓 📰 🗸	
<b>固</b> 件 升級 切换	★ 名称 3 <sup>^</sup> 修改日期	12.10
2 固件版本: Loader版本: 芯片信息: 固件:		
	● 《 网络 文仕文(別) undate ing	4 #T#F(0)
	文件类型(T): Firmware(*.ing), Loader(*.bin) ~	取消
没有发现设备		标题 4

Plug the USB cable into one of the bottom port of the duallayer USB3.0, and the other end into the PC.



Press and hold the recovery button and turn on the power until the burn tool displays "A LOADER device is recognized", click Upgrade.





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# **2.** Function Description

# 2.1 Hardware interface diagram



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#### 2.2 System Access

#### 2.2.1 Serial port access:

Prepare a serial cable\*1, connect it to the debug port, and connect the other end to the PC. open Device Manager->Port.

Check the recognized port number. Then open the serial debugging software and select COM port with baud rate 1500000.



Silicon Labs CP210x USB to UART Bridge (COM6

- 💭 打印机端口 (LPT1)
- ₩ 通信端口 (COM1)
- ₩ 通信端口 (COM2)

### 2.2.2 Graphical interface access:

Connect the board and monitor with HDMI cable, enter the desktop, click

on the bottom left corner -> System Tools - > LXTerminal to open the terminal software, enter "sudo su" to log in.



### 2.2.3 SSH remote connection: :

Connect PC and the board on the same LAN, get the IP address and use SSH to connect through the serial port tool (SecureCRT/TeraTerm) Protocol: SSH2 Username: linaro Password: linaro

Enter Secu	re Shell Password	×
linaro@192. Please enter	168. 1. 104 requires a password. a password now.	ОК
		Cancel
<u>U</u> sername:	linaro	]
Password:	•••••	]
Save pas	sword	Skip

🔚 192.168.1.104 - SecureCRT

20.00

ł	ile Edit View Options Transfer Script Tools Window Help
	: 🗲 🛱 🕫 Enter host <alt+r> 🛛 🛱 🎁 🖨 🏟 📾 🍞 🏼 🖓</alt+r>
S	✓ 192.168.1.104
essi.	Linux linaro-alip 4.19.172 #28 SMP Mon Dec 26 09:42:09 CST 2022 aarch64
on Manage	The programs included with the Debian GNU/Linux system are free software; the exact distribution terms for each program are described in the individual files in /usr/share/doc/*/copyright.
25	Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent permitted by applicable law. linaro@linaro-alip:~\$ sudo su root@linaro-alip:/home/linaro#

## **2.3 Wired Ethernet**

1) Power on the board, connect the network cable to the port (J24/J25).

2) Execute the command "ifconfig" to see the IP address or open the browser to check whether can browse the web normally.

root@linaro-alip:~# ifconfig
eth0: flags=4163 <up,broadcast,running,multicast> mtu 1500</up,broadcast,running,multicast>
inet 192.168.1.104 netmask 255.255.255.0 broadcast 192.168.1.255
inet6 fe80::57e6:7b7a:60d4:cc80 prefixlen 64 scopeid 0x20 <link/>
ether ac:db:da:59:8a:f4 txqueuelen 1000 (Ethernet)
RX packets 6 bytes 934 (934.0 B)
RX errors 0 dropped 0 overruns 0 frame 0
TX packets 21 bytes 2192 (2.1 KiB)
TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0
device interrupt 41
ethl: flags=4099 <up,broadcast,multicast> mtu 1500</up,broadcast,multicast>
ether ac:db:da:59:8a:f5 txqueuelen 1000 (Ethernet)
RX packets 0 bytes 0 (0.0 B)
RX errors 0 dropped 0 overruns 0 frame 0
TX packets 0 bytes 0 (0.0 B)
TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0
device interrupt 51

# 2.4 TF Card

1) Insert the TF card (hot-swappable) into the slot.

2)Through command "fdisk -I" to view partition information//View partition

3) Through command "df -h" to check the mounting status//View mount



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# 2.5 WiFi

Connected the antenna like the picture below:



Click on the network in the bottom right corner of the desktop Select WiFi connection





Connected successfully



# 2.6 Bluetooth

Same steps as WiFi to connect two antennas. Click on the Bluetooth icon in the bottom right corner and select "Devices"



Click "search" to search, pair and connect Bluetooth devices.



# 2.7 USB

Access U disk, interface will pop-up window, click OK and open to check the content of U disk.

	Removable medium is inserted	
(and the second	Type of medium: removable disk	
Please	select the action you want to perform:	
E Op	en in File Manager	

# 2.8 Audio interface

1) Access 4pin speaker (no earphones), play music **aplay** -**Dhw:0,0 test.wav** (Music file name). The sound came from the speaker.

2) Access 2pin MIC and enter the command "arecord-Dhw :0,0 -f dat -r 48000 -t wav -c 2 test.wav"to record. Press Ctrl+C to end the recording. Then enter "aplay-Dhw :0,0 test.wav" to play the recording.



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coot@linaro-alip:/media/linaro/USB/vedio/常用测试音频/wav# arecord -Dhw:0,0 -f dat -r 48000 -t wav -c 2 test.wav Recording WAVE 'test.wav' : Signed 16 bit Little Endian, Rate 48000 Hz, Stereo [ 380.187949] Entering es8388\_set\_dai\_sysclk [ 380.188036] #83xx#check with es8388\_pcm\_hw\_params() 905 rate[48000Hz with 12288000Hz MCLK] cnt[4][12] [ 380.189695] #83xx#check with es8388\_pcm\_hw\_params() 955 rate[48000Hz with 12288000Hz MCLK] cnt[4][12] [ 380.189695] #83xx#check with es8388\_pcm\_hw\_params() 955 rate[48000Hz with 12288000Hz MCLK] cnt[4][12] [ CAborted by signal Interrupt... ccoot@linaro-alip:/media/linaro/USB/vedio/常用测试音频/wav# []

3) Access earphones (connect earphones and speaker at the same time, priority earphone output), play music **aplay** -**Dhw:0,0 test.wav** (Music file name). The sound came from the speaker.

root@linaro-alip:/media/linaro/USB/vedio/常用测试音频/wav#
root@linaro-alip:/media/linaro/USB/vedio/常用测试音频/wav# aplay -Dhw:0,0 101-red_hot_chili_peppers-dani_california.wav
Playing WAVE '101-red_hot_chili_peppers-dani_california.wav' : Signed 16 bit Little Endian, Rate 44100 Hz, Stereo
Warning: rate is not accurate (requested = 44100Hz, got = 48000Hz)
please, try the plug plugin
[ 355.650723] Entering es8388_set_dai_sysclk
[ 355.650757] #83xx#check with es8388_pcm_hw_params() 905 rate[48000Hz with 12288000Hz MCLK] cnt[2][8]
[ 355.652555] #83xx#check with es8388 pcm hw params() 955 rate[48000Hz with 12288000Hz MCLK] cnt[2][8]
[ 355.657536] #83xx-01#check es8388_DEF_VOL with es8388_mute 990 cnt[2] [30 : 30]
[ 356.073391] [dhd-wlan0] wl_run_escan : LEGACY_SCAN sync ID: 8, bssidx: 0
- 2 · · · · · · · · · · · · · · · · · ·

### 2.9 4G LTE

1) Connect 4G LTE module, then connect the antenna, plug in 4G SIM card, and enter the command "ifconfig" on the terminal to check whether ppp0 node is obtained.



### 2.10 HDMI

Use HDMI cable to connect the board and HDMI display. After power-on, the HDMI display can be normal means ok.

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# 2.11 SSD

1) Switch on	SSD							
2) <b>fdisk -l</b> /	/View p	artition						
3) <mark>df -h</mark> //\	/iew mo	ount						
root@linaro-al: Disk /dev/ram0; Units: sectors Sector size (lo I/O size (minir	ip:~# fdi : 4 MiB, of 1 * 5 ogical/ph num/optim	sk -1 4194304 by 12 = 512 b ysical): \$ al): 4096	ytes, 8192 bytes 512 bytes bytes / 4	2 sect / 409 1096 by	ors 6 bytes ytes			
Disk /dev/mmcb2 Units: sectors Sector size (10 I/O size (minin Disklabel type) Disk identifie)	lk0: 7.3 of 1 * 5 ogical/ph num/optim : gpt r: B94600	GiB, 7818: 12 = 512 } ysical): \$ al): 512 } 00-0000-41	182656 byt bytes 512 bytes bytes / 51 059-8000-1	ces, 19 / 512 .2 byte .C8F000	5269888 s bytes es 003FF2	ectors		
Device	Start	End	Sectors	Size	Type			
/dev/mmcblk0pl	16384	24575	8192	4M	unknown			
/dev/mmcblk0p2	24576	32767	8192	4M	unknown			
/dev/mmcblk0p3	32768	98303	65536	32M	unknown			
/dev/mmcblk0p4	98304	163839	65536	32M	unknown			
/dev/mmcblk0p5	163840	229375	65536	32M	unknown			
/dev/mmcblk0p6	229376	12812287	12582912	6G	unknown			
/dev/mmcblk0p7	12812288	13074431	262144	128M	unknown			
/dev/mmcblk0p8	13074432	13090815	16384	8M	unknown			
/dev/mmcblk0p9	13090816	15269823	2179008	1G	unknown			
Disk /dev/nvme( Disk model: Ler Units: sectors Sector size (10 I/O size (minin root@linaro-al:	Dnl: 119. hovo SL70 of 1 * 5 ogical/ph num/optim ip:~# df	2 GiB, 128 0 PCI-E M 12 = 512 } ysical): 5 al): 512 } -h	8035676160 2 128G bytes 512 bytes bytes / 51	) byte: / 512 .2 byte	s, 250069 bytes es	680 sector	5	
Filesystem	Size U	sed Avail	Use% Moun	ited of	n			
udev	853M	0 853M	0% /dev					
tmpis	185M	11M 175M	6% /run	1				
/dev/mmcblk0p6	5.9G 2	.6G 3.1G	46% /					
tmpfs	922M	0 922M	0% /dev	/shm				
tmpis	5.0M 4	.0K 5.0M	1% /run	1/lock				
tmpfs	922M	0 922M	0% /sys	s/fs/co	group			
/dev/nvme0nl	117G	11G 101G	10% /mnt	/ssd	10-2015			
tmpfs	185M 4	.OK 185M	l% /run	/user,	/1000			
/dev/mmcblk0p9	1016M 2	.7M 997M	1% /med	lia/lin	naro/c9bl	174b-f335-	422d-b34c-	e53ec315de7k
/dev/mmcblk0p7	126M	13M 107M	11% /med	lia/lin	naro/b709	e899-101d-	43e5-93cb-	a36a5e05ddeo
tmpfs	185M	0 185M	0% /run	/user/	/0			



# 2.12 LVDS&touch



1) As shown in the picture, connect LVDS with the board, paying attention to the direction of the first foot.

2) Power on and start the device. Check whether LVDS can display the desktop properly.

3) touch any app icon with your finger that can open means "touch" is normal

### 2.13 Camera

1) Connected camera to interface.

2) Click on the bottom left corner of the desktop-> sound&video->cheese open. The screen can displays what the camera show is ok



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### 2.14 SPI

1) Short-circuit connected Pin 8/10 of J15.



2) Copy the file"spidev\_test" to the board.

3) Enter into the store path"spidev\_test" .

Run the command./spidev\_test -v // to check whether the TX and RX output are consistent. If they are consistent, the function is normal.



# 2.15 UART

1) Use DuPont cable to connect the TX, RX and 11/13 pins of J15

2) Enter the command "minicom -s" in the terminal of the development board, select "serial port setup", press the "A" button to change "/dev/modem" to "/dev/ttyS9" and enter to save. Press the "F" button again to change "YES" to "NO" and enter to save and exit

3) Select "Save setup as dfl", then select "Exit" enter "minicom"

4) Open another terminal software of the PC, change the port to the recognized port number (Device Manager - > Port View), and select 115200 baud rate

a Term: Serial port	setup		
Port:	COM6	$\sim$	ОК
Baud rate:	115200	~	
Data:	8 bit	~	Cancel
Parity:	none	$\sim$	
Stop:	1 bit	$\sim$	Help
<u></u>	DODO		

The two windows send data to each other and receive it successfully.



The remaining UART ports are ttyS0 corresponding to J15 5/7 pin, ttyS4 corresponding to J15 18/20 pin, ttyS5 corresponding to J15 17/19 pin, the operation steps are the same

### 2.16 CAN

1) Short-circuit access 23/24 pins of J15, connect network cable

2) apt-get install can-utils

3) Execute the command:

ifconfig -a

ip link set can0 down

ip link set can0 type can bitrate 1000000 dbitrate 1000000 fd on

ip -details link show can0

ip link set can0 up

candump can0,#fffffff &

io -4 0xfe580000 0x8405

cansend can0 123#12345678

4) Print can0 123 [4] 12 34 56 78

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root@linaro-alip:~# ip link set can0 down root@linaro-alip:~# [ 229.106038] [dhd-wlan0] wl\_run\_escan : LEGACY\_SCAN sync ID: 6, bssidx: ip link set can0 type can bitrate 1000000 dbitrate 1000000 fd on root@linaro-alip:~# ip -details link show can0 2: can0: <NOARP,ECHO> mtu 72 qdisc noop state DOWN mode DEFAULT group default qlen 10 link/can promiscuity 0 minmtu 0 maxmtu 0 can <FD> state STOPPED (berr-counter tx 0 rx 0) restart-ms 0 bitrate 1000000 sample-point 0.750 tq 10 prop-seg 37 phase-seg1 37 phase-seg2 25 sjw 1 rockchip\_canfd: tseg1 1..128 tseg2 1..128 sjw 1..128 brp 1..256 brp-inc 2 dbitrate 1000000 dsample-point 0.750 dtq 50 dprop-seg 7 dphase-seg1 7 dphase-seg2 5 dsjw 1 rockchip\_canfd: dtseg1 1..32 dtseg2 1..16 dsjw 1..16 dbrp 1..256 dbrp-inc 2 clock 20000000numtxqueues 1 numrxqueues 1 gso max size 65536 gso max segs 65535 root@linaro-alip:~# ip link set can0 up root@linaro-alip:~# [ 239.189565] IPv6: ADDRCONF(NETDEV UP): can0: link is not ready 239.189728] IPv6: ADDRCONF(NETDEV CHANGE): can0: link becomes ready root@linaro-alip:~# candump can0,#ffffffff & [1] 21218 Windows oot@linaro-alip:~# cansend can0 123#1234567 can0 123 [4] 12 34 56 78

# 2.17 IR

1) Enter "evtest" in the terminal and select "0"

2) Press the up, down, left and right buttons of the infrared remote control, it will show logo information.

sting (interrupt to exit)	
rent: time 1672297054.647337, type 1 (EV_KEY), code 108 (KEY_DOWN), value 1	
rent: time 1672297054.647337, SYN_REPORT	
259.884090] rockchip-vop2 fe040000.vop: [drm:vop2_crtc_atomic_enable] Update mod	e to
type: 7 for vp2	
259.927322] panel_simple_enable	
rent: time 1672297054.831151, type 1 (EV_KEY), code 108 (KEY_DOWN), value 0	
rent: time 1672297054.831151, SYN_REPORT	
rent: time 1672297055.837550, type 1 (EV_KEY), code 108 (KEY_DOWN), value 1	
rent: time 1672297055.837550, SYN_REPORT	
rent: time 1672297056.021141, type 1 (EV_KEY), code 108 (KEY_DOWN), value 0	
rent: time 1672297056.021141, SYN_REPORT	
rent: time 1672297056.715965, type 1 (EV_KEY), code 103 (KEY_UP), value 1	
rent: time 1672297056.715965, SYN_REPORT	
rent: time 1672297056.804478, type 1 (EV_KEY), code 103 (KEY_UP), value 0	
ent: time 1672297056.804478, SYN_REPORT	
rent: time 1672297057.028132, type 1 (EV_KEY), code 103 (KEY_UP), value 1	
rent: time 1672297057.028132, SYN_REPORT	
rent: time 1672297057.117799, type 1 (EV_KEY), code 103 (KEY_UP), value 0	
rent: time 1672297057.117799, SYN_REPORT	
rent: time 1672297057.741485, type 1 (EV_KEY), code 28 (KEY_ENTER), value 1	

# 2.18 RTC

- 1) Connect RTC battery
- 2) date -s "2023-2-9 23:58:00" //could set a different time
- 3) hwclock -w // Write hardware time
- 4) hwclock -r // Read hardware time
- 5) date // Check the system time
- 6) Waiting 1 minute to sync to hardware time
- 7) Power off and waiting for over 1 minute before starting
- 8) date or hwclock -r check if the desktop time is advancing normally